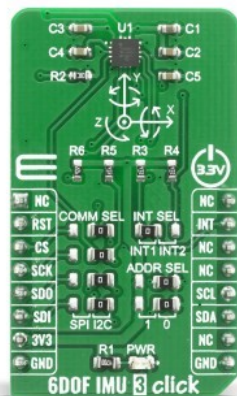


6DOF IMU 3 Click



PID: MIKROE-4086

6 DOF IMU 3 Click is a complete 6-axis detection development board suitable for movement and position tracking devices. This Click board features the compact FXOS8700CQ motion sensor from NXP, an integrated 3-axis linear accelerometer and 3-axis magnetometer combined in one package. The device supports selectable I2C or point-to-point SPI serial interface with 14-bit accelerometer and 16-bit magnetometer which are combined with a high-performance ASIC to enable an eCompass solution capable of a typical orientation resolution of 0.1° and sub-5° compass heading accuracy for many applications.

6 DOF IMU 3 Click is supported by a mikroSDK compliant library, which includes functions that simplify software development. This Click board™ comes as a fully tested product, ready to be used on a system equipped with the mikroBUS™ socket.

How does it work?

The 6 DOF IMU 3 Click is based around the [FXOS8700CQ](#), which is a small, low-power, 3-axis, linear accelerometer and 3-axis magnetometer combined into a single package, from [NXP](#). The device features a selectable I2C or point-to-point SPI serial interface with 14-bit accelerometer and 16-bit magnetometer ADC resolution along with smart-embedded functions. The FXOS8700CQ has dynamically selectable acceleration full-scale ranges of ± 2 g/ ± 4 g/ ± 8 g and a fixed magnetic measurement range of ± 1200 μ T. Output data rates (ODR) from 1.563 Hz to 800 Hz are selectable by the user for each sensor. Interleaved magnetic and acceleration data is available at ODR rates of up to 400 Hz.

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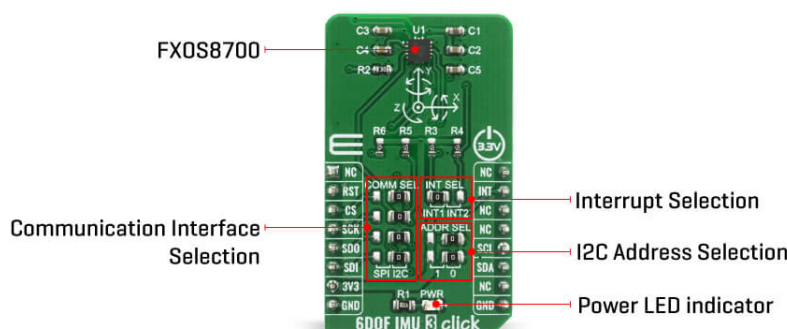
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Sensitivity of the sensor is represented in mg/LSB for the accelerometer and $\mu\text{T/LSB}$ for the magnetometer. The magnetometer sensitivity is fixed at $0.1 \mu\text{T/LSB}$. The accelerometer sensitivity changes with the full-scale range selected by the user. Accelerometer sensitivity is 0.244 mg/LSB in 2 g mode, 0.488 mg/LSB in 4 g mode, and 0.976 mg/LSB in 8 g mode, making it ideal for applications such as used for security, like motion detection, door opening, smart home applications, robotics and unmanned aerial vehicles (UAVs) with electronic compass (e-compass) function, in medical purposes, like patient monitoring, fall detection and more.

6DOF IMU 3 Click supports both SPI and I2C communication interfaces, allowing it to be used with a wide range of different MCUs. The communication interface can be selected by moving SMD jumpers grouped under the COM SEL to an appropriate position (SPI or I2C). The slave I2C address can also be configured by an SMD jumper when the Click board™ is operated in the I2C mode. An SMD jumpers labeled as ADDR SEL is used to set the least significant bit (LSB) of the I2C address. The I2C interface is compliant with fast mode (400 kHz), and normal mode (100 kHz) I2C standards, while the SPI interface is a classical master/slave serial port. The FXOS8700CQ is always considered as the slave and thus is never initiating the communication.

This Click Board™ is designed to be operated only with 3.3V logic level. A proper logic voltage level conversion should be performed before the Click board™ is used with MCUs with logic levels of 5V.

Specifications

Type	Acceleration,Magnetic,Motion
Applications	For security, like motion detection, door opening, smart home applications, robotics, and unmanned aerial vehicles (UAVs) with electronic compass (e-compass) function, medical, like patient monitoring, fall detection, and rehabilitation, augmented reality (AR), gaming, and real-time activity analysis, etc.
On-board modules	FXOS8700CQ is a small, low-power, 3-axis, linear accelerometer and 3-axis, magnetometer combined into a single package
Key Features	The 14-bit accelerometer and 16-bit

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	magnetometer are combined with a high-performance ASIC to enable an eCompass solution capable of a typical orientation resolution of 0.1° and sub-5° compass heading accuracy
Interface	I2C,SPI
Feature	No ClickID
Compatibility	mikroBUS™
Click board size	M (42.9 x 25.4 mm)
Input Voltage	3.3V

Pinout diagram

This table shows how the pinout on 6DOF IMU 3 Click corresponds to the pinout on the mikroBUS™ socket (the latter shown in the two middle columns).

Notes	Pin					Pin	Notes
	NC	1	AN	PWM	16	NC	
Reset	RST	2	RST	INT	15	INT	Interrupt
SPI Chip Select	CS	3	CS	RX	14	NC	
SPI Clock	SCK	4	SCK	TX	13	NC	
SPI Data OUT	SDO	5	MISO	SCL	12	SCL	I2C Clock
SPI Data IN	SDI	6	MOSI	SDA	11	SDA	I2C Data
Power Supply	3.3V	7	3.3V	5V	10	NC	
Ground	GND	8	GND	GND	9	GND	Ground

Onboard settings and indicators

Label	Name	Default	Description
LD1	PWR	-	Power LED Indicator
JP1	INT SEL	Left	Interrupt pin selection, left position INT1, right position INT2
JP2	ADDR SEL	Right	I2C address selection pin SA0, left position 3V3 (H), right position 0V (L)
JP3	ADDR SEL	Right	I2C address selection pin SA1, left position 3V3 (H), right position 0V (L)
JP4	COMM SEL	Right	Communication selection, left position SPI CS pin, right position I2C SA1 pin
JP5	COMM SEL	Right	Communication selection, left position SPI SCK pin, right

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			position I2C SCL pin
JP6	COMM SEL	Right	Communication selection, left position SPI MISO pin, right position I2C SA0 pin
JP7	COMM SEL	Right	Communication selection, left position SPI MOSI pin, right position I2C SDA pin

Software Support

We provide a library for the 6DOF IMU 3 Click on our [LibStock](#) page, as well as a demo application (example), developed using MikroElektronika [compilers](#). The demo can run on all the main MikroElektronika [development boards](#).

Library Description

The library covers all the necessary functions to control 6DOF IMU 3 click board. Library performs a standard I2C and SPI interface communication.

Key functions:

- C6DOFIMU3_RETVAL_T c6dofimu3_check_id (void) - Check ID function.
- void c6dofimu3_default_config (void) - Set default sensor configuration function.
- void c6dofimu3_get_data (c6dofimu3_accel_t *accel_data, c6dofimu3_mag_t *mag_data); - Read Accel and Magnetometer data function

Examples description

The application is composed of three sections :

- System Initialization - Initializes I2C and start to write log.
- Application Initialization - Initialization driver enables - I2C, check communication by read device ID, initializing the device, set default configuration for accelerometer and magnetometer, also write log.
- Application Task - (code snippet) This is an example which demonstrates the use of 6DOF IMU 3 Click board. Measured and display Accel and Mag data coordinates values for X-axis, Y-axis and Z-axis. Results are being sent to the Usart Terminal where you can track their changes. All data logs write on USB uart changes for every 500 ms.

The full application code, and ready to use projects can be found on our [LibStock](#) page.

Other mikroE Libraries used in the example:

- I2C or SPI
- UART
- Conversions

Additional notes and informations

Depending on the development board you are using, you may need [USB UART click](#), [USB UART 2 click](#) or [RS232 click](#) to connect to your PC, for development systems with no UART to USB

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interface available on the board. The terminal available in all MikroElektronika [compilers](#), or any other terminal application of your choice, can be used to read the message.

mikroSDK

This Click board™ is supported with [mikroSDK](#) - MikroElektronika Software Development Kit. To ensure proper operation of mikroSDK compliant Click board™ demo applications, mikroSDK should be downloaded from the [LibStock](#) and installed for the compiler you are using.

For more information about mikroSDK, visit the [official page](#).

Resources

[mikroBUS™](#)

[mikroSDK](#)

[Click board™ Catalog](#)

[Click Boards™](#)

Downloads

[6DOF IMU 3 click 2D and 3D files](#)

[FXOS8700CQ datasheet](#)

[6DOF IMU 3 click example on Libstock](#)

[6DOF IMU 3 click schematic](#)

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