

# KA7405D

## 2-Channel DC Motor Drive IC

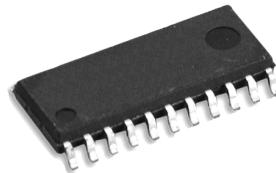
### Features

- Output current up to 1.5A (Each channel).
- 4-function modes (CW, CCW, stop and brake) are controlled by 2-logic circuits.
- Operating voltage range: V<sub>CC</sub> = 2.5 ~ 6.0V.
- Built-in spike killer diode.
- Low saturation voltage.

### Description

The KA7405D is a monolithic integrated circuit, and suitable for the zoom and reel motor driver for camera, tape deck, any other consumer and industrial applications.

22-SOP-300



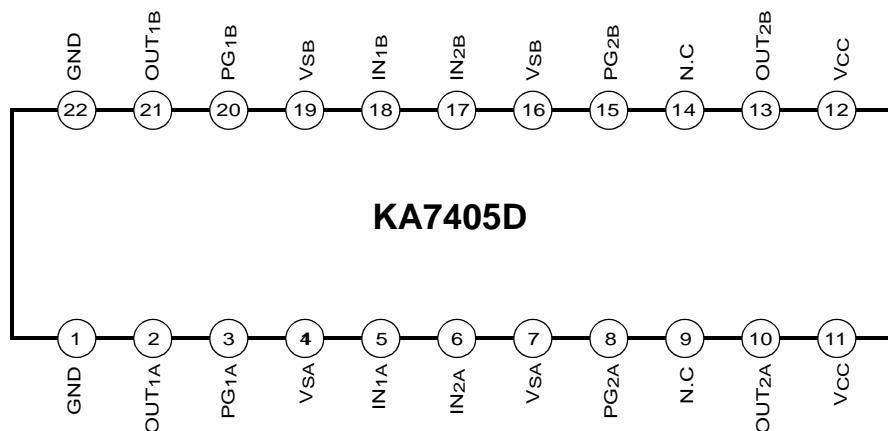
### Typical Applications

- Camera zoom and film motors
- General DC motor

### Ordering Information

Device	Package	Operating Temp.
KA7405D	22-SOP-300	-25°C to +75°C

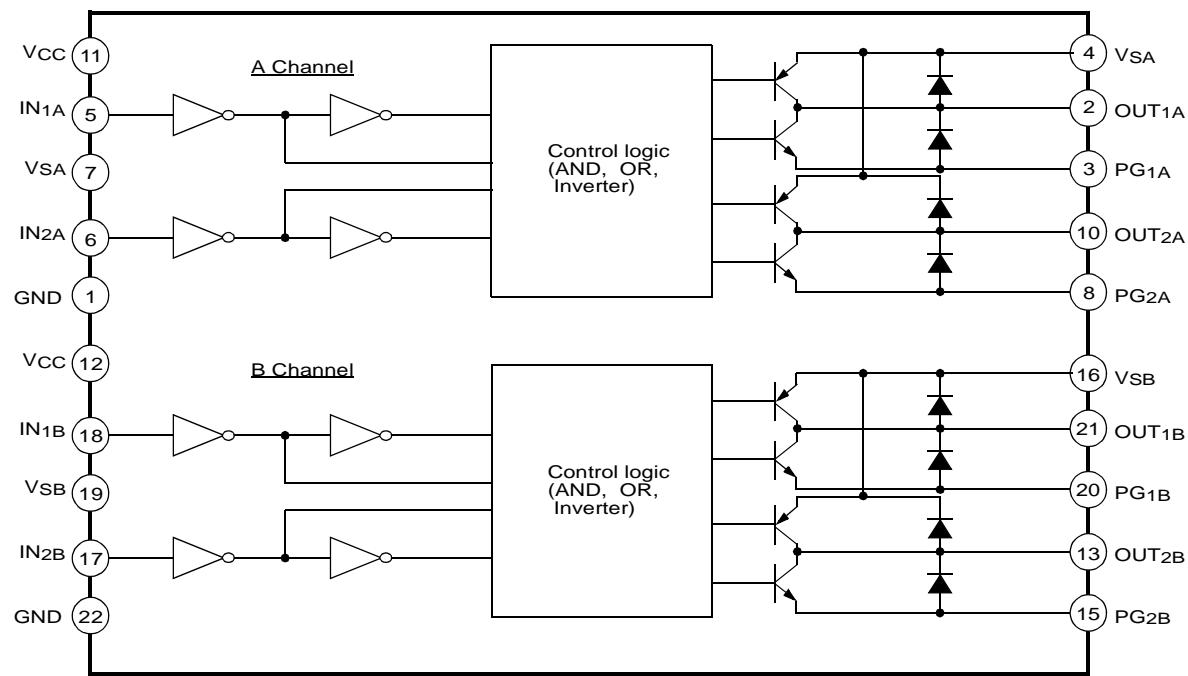
## Pin Assignments



## Pin Definitions

Pin Number	Pin Name	I/O	Pin Function Description	Remark
1	GND	-	Signal ground	-
2	OUT1A	O	Output 1	Channel A
3	PG1A	-	Power ground 1	Channel A
4	VSA	-	Output supply voltage	Channel A
5	IN1A	I	Input 1	Channel A
6	IN2A	I	Input 2	Channel A
7	VSA	-	Output supply voltage	Channel A
8	PG2A	-	Power ground 2	Channel A
9	NC	-	No connection	-
10	OUT2A	O	Output 2	-
11	VCC	-	Supply voltage	-
12	VCC	-	Supply voltage	-
13	OUT2B	O	Output 2	Channel B
14	NC	-	No connection	-
15	PG2B	-	Power ground 2	Channel B
16	VSB	-	Output supply voltage	Channel B
17	IN2B	I	Input 2	Channel B
18	IN1B	I	Input 1	Channel B
19	VSB	-	Output supply voltage	Channel B
20	PG1B	-	Power ground 1	Channel B
21	OUT1B	O	Output 1	Channel B
22	GND	-	Signal ground	-

## Internal Block Diagram



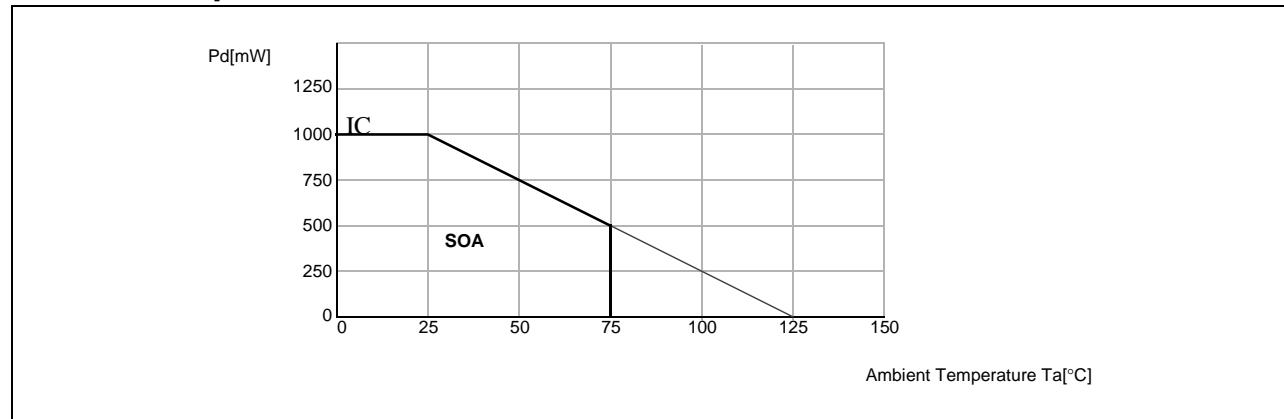
## Equivalent Circuits

Description	Pin No.	Internal Circuit
Control Input		
IN1A	5	
IN2A	6	
IN1B	18	
IN2B	17	
VCC	11, 12	
GND	1, 22	
		<p>The internal circuit for the control input section consists of a Darlington pair. The collector of the first transistor is connected to pin 11 (VCC) through a 30kΩ resistor. The base of the second transistor is connected to the collector of the first, and its collector is connected to pin 12 (GND) through a 30kΩ resistor. The emitter of the second transistor is connected to ground (pin 1). The bases of both transistors are connected to pins 5 (IN1A) and 18 (IN1B) via resistors, and also to pins 6 (IN2A) and 17 (IN2B) via resistors. The emitters of the transistors are also connected to ground (pin 1).</p>
Motor Output		
OUT1A	2	
OUT2A	10	
OUT1B	21	
OUT2B	13	
VSA	4, 7	
VSB	16, 19	
PG1A	3	
PG2A	8	
PG1B	20	
PG2B	15	<p>The internal circuit for the motor output section features two Darlington pairs. The top pair has its collector connected to pin 21 (GND) through a 30kΩ resistor. Its base is connected to the collector of the bottom pair and to pins 4 (VSA), 7 (VSB), and 16 (PG1A) via resistors. The bottom pair's collector is connected to pin 2 (OUT1A) through a 30kΩ resistor. Its base is connected to the collector of the top pair and to pins 13 (VSA), 10 (VSB), and 19 (PG2A) via resistors. The emitters of both pairs are connected to ground (pin 1). There are also feedback paths from the collectors of the bottom pair back to their respective bases via resistors.</p>

## Absolute Maximum Ratings (Ta = 25°C)

Parameter	Symbol	Value	Unit
Power supply voltage	V <sub>CCMAX</sub>	6.0	V
Channel supply voltage	V <sub>SMAX</sub>	6.0	V
Power dissipation	P <sub>D</sub>	1000	mW
Operating temperature	T <sub>OPR</sub>	-25 ~ +75	°C
Storage temperature	T <sub>STG</sub>	-40 ~ +125	°C
Output current	I <sub>OMAX</sub>	1.5	A

## Power Dissipation Curve



## Recommended Operating Conditions (Ta = 25°C)

Parameter	Symbol	Min.	Typ.	Max.	Unit
Operating supply voltage	V <sub>CC</sub>	2.5	-	6.0	V

## Electrical Characteristics

(VCC=3V, Ta=25°C, unless otherwise specified)

Parameter	Symbol	Conditions	Min.	Typ.	Max.	Unit
Supply current 1	I <sub>CC1</sub>	V <sub>IN</sub> (all) = 0V, V <sub>CC</sub> =5V	-	0.1	10	µA
Supply current 2	I <sub>CC2</sub>	V <sub>IN1</sub> =3V, V <sub>CC</sub> =5V	-	15	30	mA
Supply current 3	I <sub>CC3</sub>	V <sub>IN2</sub> =3V, V <sub>CC</sub> =5V	-	15	30	mA
Supply current 4	I <sub>CC4</sub>	V <sub>IN</sub> =3V	-	30	50	mA
Input current	I <sub>IN</sub>	V <sub>CC</sub> =6V, V <sub>IN</sub> =2V	-	45	80	µA
Leakage current	I <sub>IK</sub>	V <sub>CC</sub> =5V	-	0.1	10	µA
Upper spark diode forward voltage	V <sub>SF1</sub>	I <sub>O</sub> =500mA	-	1.0	1.7	V
Lower spark diode forward voltage	V <sub>SF2</sub>	I <sub>O</sub> =500mA	-	1.0	1.7	V
Output saturation voltage (1A)	V <sub>O1A</sub>	I <sub>OA</sub> =300mA, V <sub>IN1A</sub> =3V	-	0.45	0.70	V
Output saturation voltage (1B)	V <sub>O1B</sub>	I <sub>OB</sub> =300mA, V <sub>IN1B</sub> =3V	-	0.45	0.70	V
Output saturation voltage (2A)	V <sub>O2A</sub>	I <sub>OA</sub> =600mA, V <sub>IN1A</sub> =3V	-	1.0	1.5	V
Output saturation voltage (2B)	V <sub>O2B</sub>	I <sub>OB</sub> =600mA, V <sub>IN1B</sub> =3V	-	1.0	1.5	V
Output saturation voltage (3A)	V <sub>O3A</sub>	I <sub>OA</sub> =300mA, V <sub>IN2A</sub> =3V	-	0.45	0.70	V
Output saturation voltage (3B)	V <sub>O3B</sub>	I <sub>OB</sub> =300mA, V <sub>IN2B</sub> =3V	-	0.45	0.70	V
Output saturation voltage (4A)	V <sub>O4A</sub>	I <sub>OA</sub> =600mA, V <sub>IN2A</sub> =3V	-	1.0	1.5	V
Output saturation voltage (4B)	V <sub>O4B</sub>	I <sub>OB</sub> =600mA, V <sub>IN2B</sub> =3V	-	1.0	1.5	V
Output saturation voltage 5	V <sub>O5</sub>	I <sub>OB</sub> =600mA, V <sub>IN1</sub> =3V	-	0.6	0.8	V
Output saturation voltage 6	V <sub>O6</sub>	I <sub>O</sub> =600mA, V <sub>IN2</sub> =3V	-	0.6	0.8	V
Output saturation voltage 7	V <sub>O7</sub>	I <sub>O</sub> =1200mA, V <sub>IN1</sub> =3V	-	1.2	1.6	V
Output saturation voltage 8	V <sub>O8</sub>	I <sub>O</sub> =1200mA, V <sub>IN2</sub> =3V	-	1.2	1.6	V
Output sustain voltage	V <sub>SUS</sub>	I <sub>O</sub> =200mA	10	15	-	V
Output saturation low voltage A <sup>note</sup>	V <sub>O LA</sub>	V <sub>CC</sub> =1.9V, I <sub>OA</sub> =400mA	-	0.45	0.90	V
Output saturation low voltage B <sup>note</sup>	V <sub>O LB</sub>	V <sub>CC</sub> =1.9V, I <sub>OB</sub> =400mA	-	0.45	0.90	V

**Notes:**

User's option.

## Operation Truth Table

Input/Output Motor Operation	Input 1	Input 2	Output 1	Output 2	Remark
Stop	Low	Low	Off	Off	High impedance
Forward Operation	Low	High	Low	High	CW / CCW
Backward Operation	High	Low	High	Low	CCW / CW
Fast stop	High	High	Low	Low	Brake

## Typical Performance Characteristics

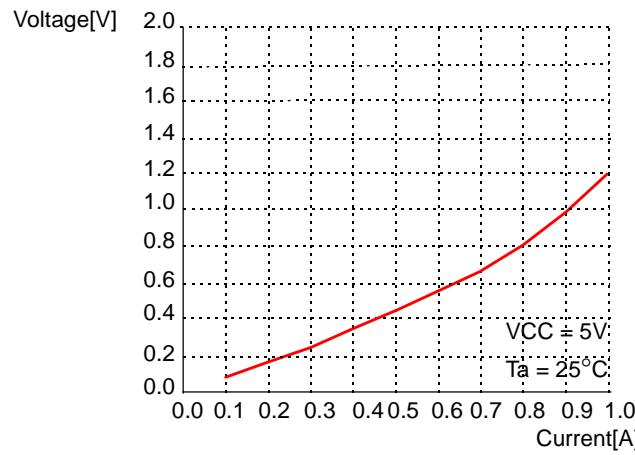


Figure 1. PNP Saturation Voltage

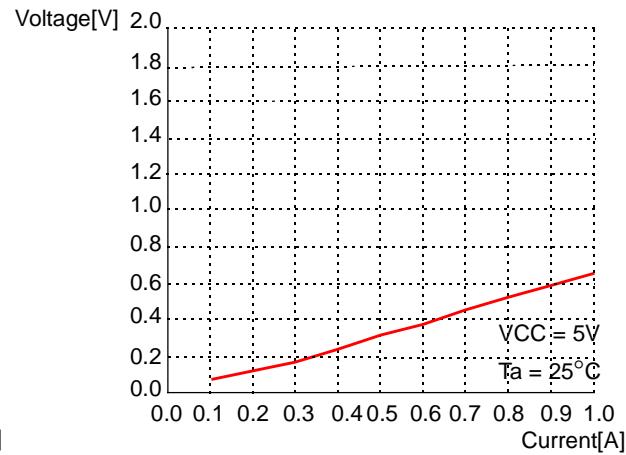
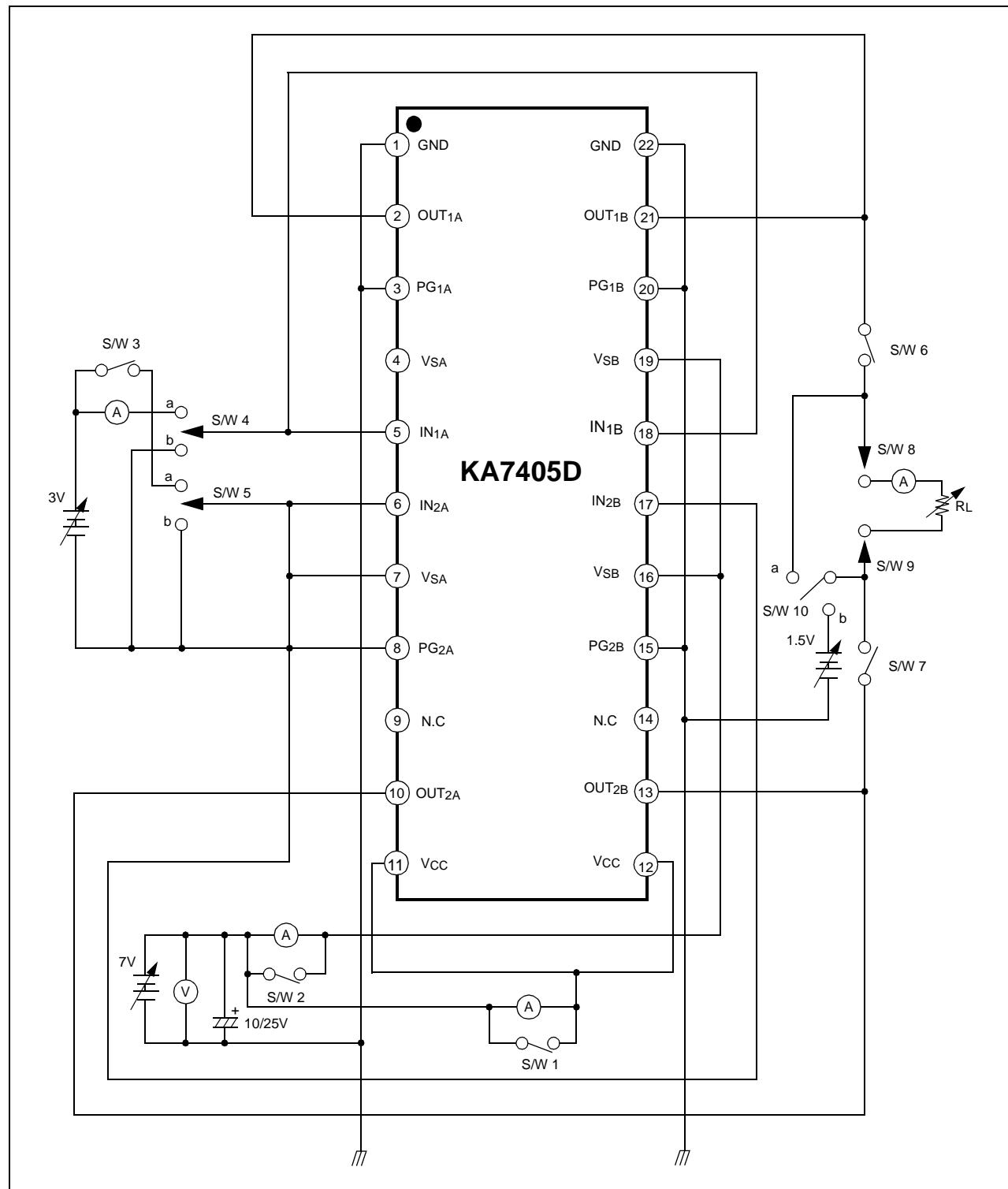


Figure 2. PNP Saturation Voltage

## Test Circuits



## Test Conditions

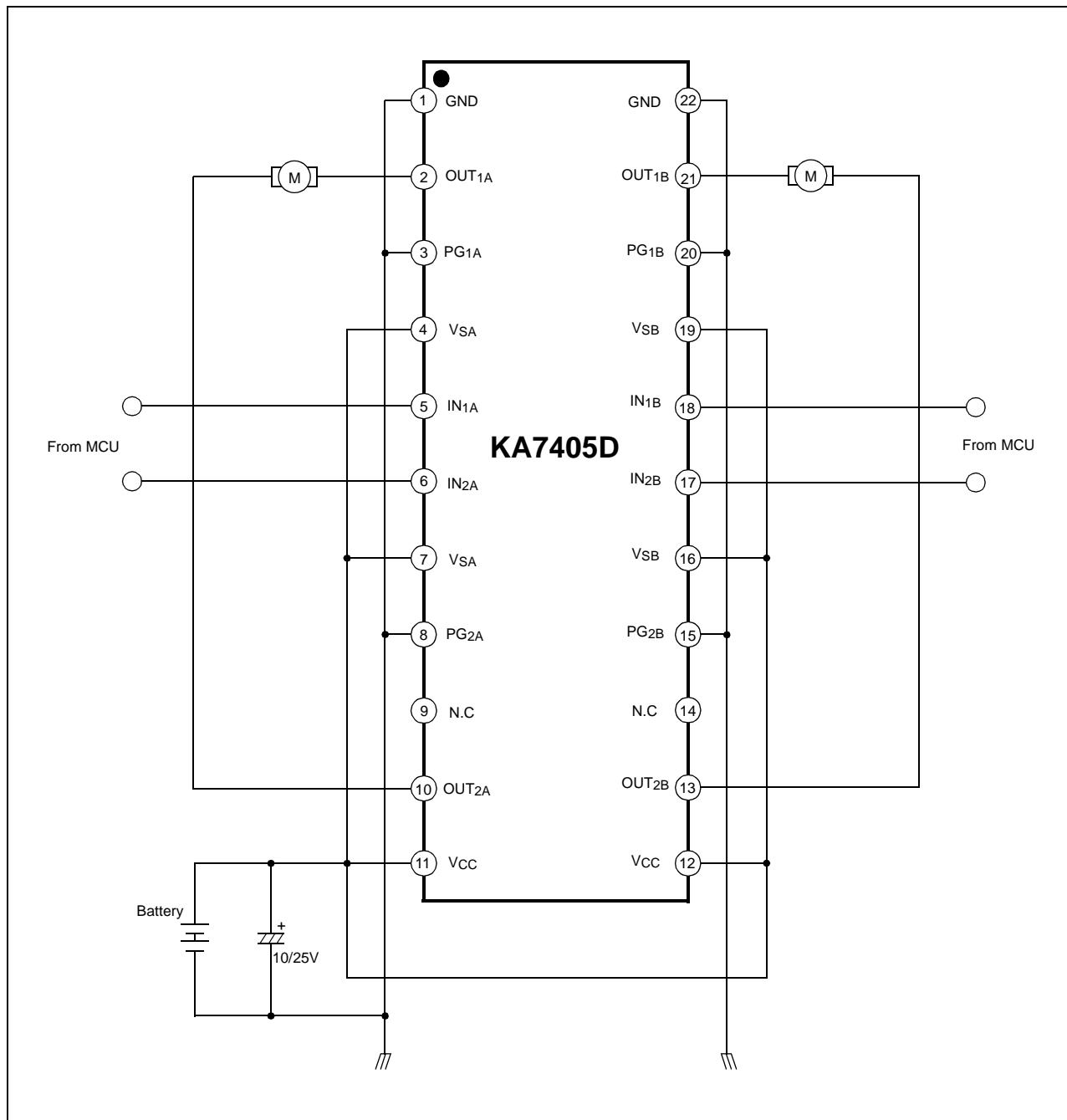
Characteristics	SW1	SW2	SW3	SW4	SW5	SW6	SW7	SW8	SW9	SW10	Remark
I <sub>CC1</sub>	Off	Off	X	b	b	Off	Off	X	X	Off	Supply current
I <sub>CC2</sub>	Off	Off	On	a	b	Off	Off	X	X	Off	Supply current
I <sub>CC3</sub>	Off	Off	On	b	a	Off	Off	X	X	Off	Supply current
I <sub>CC4</sub>	Off	Off	On	a	a	Off	Off	X	X	Off	Supply current
I <sub>IN</sub>	On	On	On	a	a	Off	Off	X	X	Off	Input current
I <sub>IK</sub>	Off	Off	Off	b	b	Off	Off	X	X	Off	Leakage current
V <sub>SF1</sub>	On	On	On	a	b	On	On	Off	Off	a	Spark diode
V <sub>SF2</sub>	On	On	On	b	a	On	On	Off	Off	b	Spark diode
V <sub>O1A</sub>	On	On	On	a	b	On	On	On	On	Off	Single mode
V <sub>O2A</sub>	On	On	On	b	a	On	On	On	On	Off	Single mode
V <sub>O3A</sub>	On	On	On	a	b	On	On	On	On	Off	Single mode
V <sub>O4A</sub>	On	On	On	b	a	On	On	On	On	Off	Single mode
V <sub>O5</sub>	On	On	On	a	b	On	On	On	On	Off	Parallel mode
V <sub>O6</sub>	On	On	On	b	a	On	On	On	On	Off	Parallel mode
V <sub>O7</sub>	On	On	On	a	b	On	On	On	On	Off	Parallel mode
V <sub>O8</sub>	On	On	On	b	a	On	On	On	On	Off	Parallel mode
V <sub>SUS</sub>	Off	Off	X	b	b	On	On	On	On	Off	Sustain voltage

**Notes:**

'X' : Don't care.

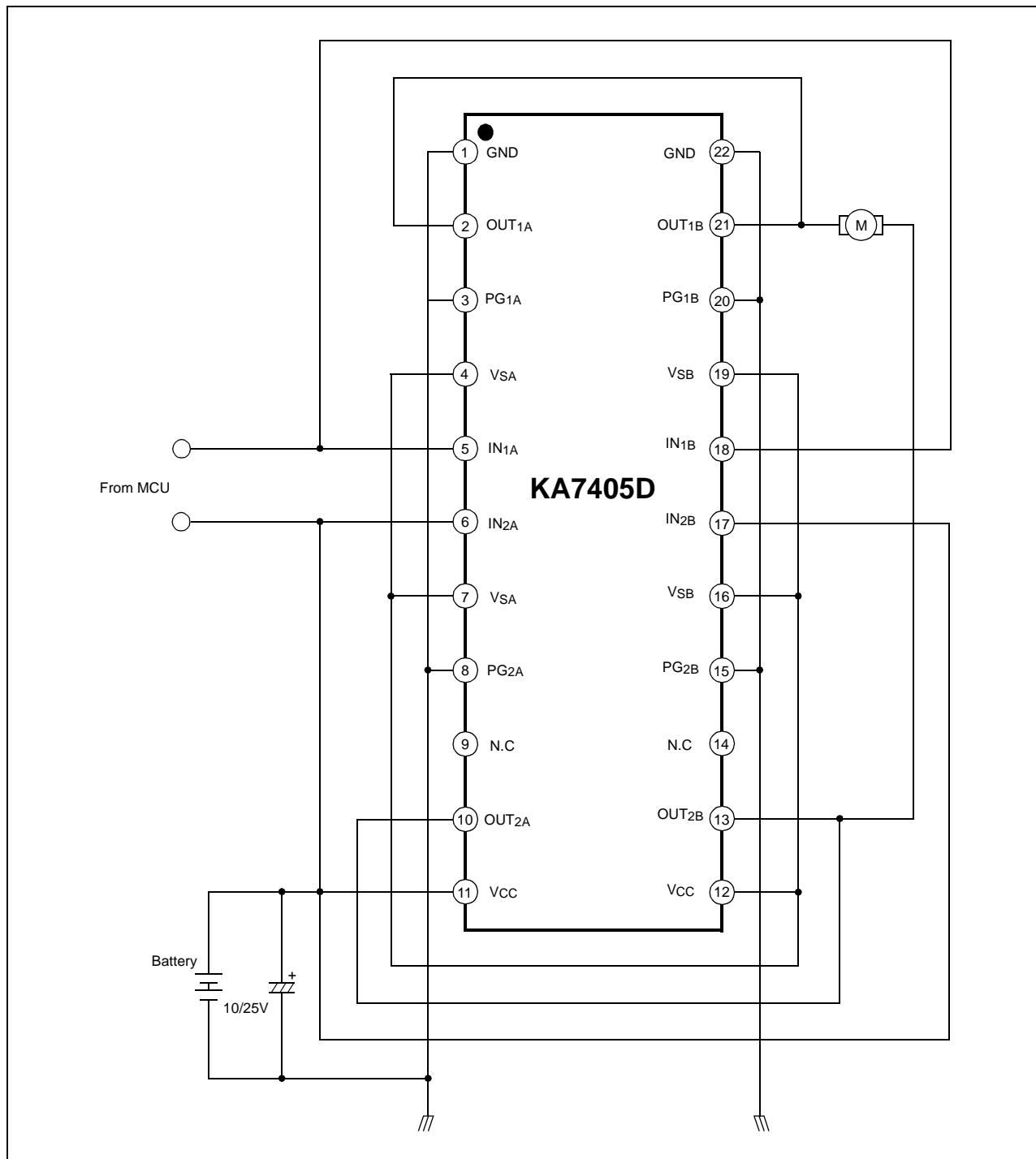
## Typical Application Circuits 1

(Single drive mode)



## Typical Application Circuits 2

(Parallel drive mode)



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## General description

The KA7405D is a monolithic integrated circuit, suitable for the zoom and reel motor driver for camera, tape deck, any other consumer and industrial applications.

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## Features

- Output current up to 1.5A (Each channel).
- 4-function modes (CW, CCW, stop and brake) are controlled by 2-logic circuits.
- Operating voltage range:  $V_{CC} = 2.5 \sim 6.0V$ .
- Built-in spike killer diode.
- Low saturation voltage.

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## Applications

- Camera zoom and film motors
- General DC motor

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Product	Product status	Package type	Leads	Packing method
KA7405D01	Not recommended for new designs	SOP	22	RAIL
KA7405D	Not recommended for new designs	SOP	22	RAIL

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