SIEMENS

Data sheet 3RM1101-1AA14



Fail-safe direct starter, 3RM1, 500 V, 0 - 0.12 kW, 0.1 - 0.5 A, 110-230 V AC, screw terminals

product brand name	SIRIUS	
product category	Motor starter	
product designation	Fail-safe direct starter	
design of the product	With electronic overload protection and safety-related disconnection	
product type designation	3RM1	
General technical data		
equipment variant according to IEC 60947-4-2	3	
product function	fail-safe direct starter	
 intrinsic device protection 	Yes	
 for power supply reverse polarity protection 	Yes	
suitability for operation device connector 3ZY12	No	
insulation voltage rated value	500 V	
overvoltage category	III	
surge voltage resistance rated value	6 kV	
maximum permissible voltage for protective separation		
 between main and auxiliary circuit 	500 V	
 between control and auxiliary circuit 	250 V	
shock resistance	6g / 11 ms	
vibration resistance	1 6 Hz, 15 mm; 20 m/s², 500 Hz	
operating frequency maximum	1 1/s	
mechanical service life (operating cycles) typical	15 000 000	
reference code according to IEC 81346-2	Q	
Substance Prohibitance (Date)	03/01/2017	
product function		
direct start	Yes	
reverse starting	No	
product function short circuit protection	No	
Electromagnetic compatibility		
EMC emitted interference according to IEC 60947-1	class A	
EMC immunity according to IEC 60947-1	Class A	
conducted interference		
 due to burst according to IEC 61000-4-4 	3 kV / 5 kHz	
 due to conductor-earth surge according to IEC 61000-4-5 	4 kV signal lines 2 kV	
 due to conductor-conductor surge according to IEC 61000-4-5 	2 kV	
 due to high-frequency radiation according to IEC 61000- 4-6 	10 V	
field-based interference according to IEC 61000-4-3	10 V/m	
electrostatic discharge according to IEC 61000-4-2	6 kV contact discharge / 8 kV air discharge	
conducted HF interference emissions according to CISPR11	Class B for domestic, business and commercial environments; Class A for industrial environments at 110 V DC	

field-bound HF interference emission according to CISPR11	Class B for domestic, business and commercial environments; Class A for industrial environments at 110 V DC
Safety related data	TO SOLITION OF THE SOLITION OF
safety device type according to IEC 61508-2	Type B
B10d value	1 300 000
Safety Integrity Level (SIL) according to IEC 61508	3
SIL Claim Limit (subsystem) according to EN 62061	SILCL 3
performance level (PL) according to EN ISO 13849-1	e
category according to EN ISO 13849-1	4
stop category according to EN 60204-1	0
Safe failure fraction (SFF)	99 %
average diagnostic coverage level (DCavg)	99 %
diagnostics test interval by internal test function maximum	600 s
function test interval maximum	1 a
failure rate [FIT]	
 at rate of recognizable hazardous failures (λdd) 	1 400 FIT
at rate of non-recognizable hazardous failures (λdu)	16 FIT
PFHD with high demand rate according to EN 62061	2E-8 1/h
PFDavg with low demand rate according to IEC 61508	0
MTTFd	75 a
hardware fault tolerance according to IEC 61508	1
safe state	Load circuit open
protection class IP on the front according to IEC 60529	IP20
touch protection on the front according to IEC 60529	finger-safe
hardware fault tolerance according to IEC 61508 relating to ATEX	0
PFDavg with low demand rate according to IEC 61508 relating to ATEX	0.0005
PFHD with high demand rate according to EN 62061 relating to ATEX	5E-8 1/h
Safety Integrity Level (SIL) according to IEC 61508 relating to ATEX	SIL2
T1 value for proof test interval or service life according to IEC 61508 relating to ATEX	3 a
Main circuit	
Main circuit number of poles for main current circuit	3 Unitotid
Main circuit	3 Hybrid 0.1 0.5 A
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current-	Hybrid
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release	Hybrid 0.1 0.5 A
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%]	Hybrid 0.1 0.5 A 20 %; from set rated current
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 %
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value relative symmetrical tolerance of the operating frequency	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 %
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 %
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current-dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current-dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input • at DC rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input • at DC rated value • with signal <0> at DC	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A 0.12 kW
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input • at DC rated value • with signal <0> at DC • for signal <1> at DC	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A 0.12 kW
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input • at DC rated value • with signal <0> at DC • for signal <1> at DC input voltage at digital input	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.5 A 110 V 0 0.12 kW
Main circuit number of poles for main current circuit design of the switching contact adjustable current response value current of the current- dependent overload release minimum load [%] type of the motor protection operating voltage rated value relative symmetrical tolerance of the operating voltage operating frequency 1 rated value operating frequency 2 rated value relative symmetrical tolerance of the operating frequency operational current • at AC at 400 V rated value • at AC-3 at 400 V rated value • at AC-53a at 400 V at ambient temperature 40 °C rated value ampacity when starting maximum operating power for 3-phase motors at 400 V at 50 Hz Inputs/ Outputs input voltage at digital input • at DC rated value • with signal <0> at DC • for signal <1> at DC input voltage at digital input • at AC rated value	Hybrid 0.1 0.5 A 20 %; from set rated current solid-state 48 500 V 10 % 50 Hz 60 Hz 10 % 0.5 A 0.5 A 0.5 A 0.10 A 10 V 110 V 110 V 110 V 110 V 110 V 110 V

• for signal <1> at DC	1.5 mA
• with signal <0> at DC	0.25 mA
input current at digital input with signal <0> at AC	
• at 110 V	0.2 mA
● at 230 V	0.4 mA
input current at digital input for signal <1> at AC	
• at 110 V	1.1 mA
• at 230 V	2.3 mA
number of CO contacts for auxiliary contacts	1
operational current of auxiliary contacts at AC-15 at 230 V maximum	3 A
operational current of auxiliary contacts at DC-13 at 24 V maximum	1 A
Control circuit/ Control	
type of voltage of the control supply voltage	AC/DC
control supply voltage at AC	
• at 50 Hz rated value	110 230 V
at 60 Hz rated value	110 230 V
relative negative tolerance of the control supply voltage at AC at 60 Hz	15 %
relative positive tolerance of the control supply voltage at AC at 60 Hz	10 %
control supply voltage 1 at AC	
● at 50 Hz	110 230 V
● at 60 Hz	110 230 V
control supply voltage frequency	
• 1 rated value	50 Hz
2 rated value	60 Hz
relative negative tolerance of the control supply voltage at DC	15 %
relative positive tolerance of the control supply voltage at DC	10 %
control supply voltage 1 at DC rated value	110 V
operating range factor control supply voltage rated value at DC	
initial value	0.85
full-scale value	1.1
operating range factor control supply voltage rated value at AC at 50 Hz	
initial value	0.85
full-scale value	1.1
operating range factor control supply voltage rated value at AC at 60 Hz	
● initial value	0.85
full-scale value	1.1
control current at AC	
 at 110 V in standby mode of operation 	8 mA
at 230 V in standby mode of operation	6 mA
• at 110 V when switching on	40 mA
at 230 V when switching on	25 mA
at 110 V during operation	25 mA
at 230 V during operation	14 mA
control current at DC	
in standby mode of operation	4 mA
during operation	30 mA
inrush current peak	4 200 4
• at AC at 110 V	1 200 mA
• at AC at 110 V at quitabing on of mater	2 900 mA
at AC at 230 V at switching on of motor at AC at 230 V at switching on of motor	1 200 mA
at AC at 230 V at switching on of motor duration of invent pook	2 900 mA
duration of inrush current peak	1 ma
• at AC at 110 V	1 ms
• at AC at 230 V	1 ms

at AC at 110 V at switching on of motor	1 ms
at AC at 230 V at switching on of motor	1 ms
power loss [W] in auxiliary and control circuit	
• in switching state OFF	
— with bypass circuit	1.4 W
• in switching state ON	
— with bypass circuit	3.22 W
Response times	
ON-delay time	90 120 ms
OFF-delay time	60 90 ms
Power Electronics	
operational current	
 at 40 °C rated value 	0.5 A
 at 50 °C rated value 	0.5 A
 at 55 °C rated value 	0.5 A
at 60 °C rated value	0.5 A
Installation/ mounting/ dimensions	
mounting position	vertical, horizontal, standing (observe derating)
fastening method	screw and snap-on mounting onto 35 mm DIN rail
height	100 mm
width	23 mm
depth	142 mm
required spacing	
 with side-by-side mounting 	
— forwards	0 mm
— backwards	0 mm
— upwards	50 mm
— downwards	50 mm
— at the side	0 mm
for grounded parts	
— forwards	0 mm
— backwards	0 mm
— upwards	50 mm
— at the side	4 mm
— downwards	50 mm
Ambient conditions	
installation altitude at height above sea level maximum	4 000 m; For derating see manual
ambient temperature	
 during operation 	-25 +60 °C
during storage	-40 +70 °C
during transport	-40 +70 °C
environmental category during operation according to IEC 60721	3K6 (no ice formation, only occasional condensation), 3C3 (no salt mist), 3S2 (sand must not get into the devices), 3M6
relative humidity during operation	10 95 %
air pressure according to SN 31205	900 1 060 hPa
Communication/ Protocol	
protocol is supported	
PROFINET IO protocol	No
PROFIsafe protocol	No
product function bus communication	No
protocol is supported AS-Interface protocol	No
Connections/ Terminals	
type of electrical connection	screw-type terminals for main circuit, screw-type terminals for control circuit
for main current circuit	screw-type terminals
for auxiliary and control circuit	screw-type terminals
wire length for motor unshielded maximum	100 m
type of connectable conductor cross-sections for main contacts	
• solid	1x (0,5 4 mm²), 2x (0,5 2,5 mm²)
 finely stranded with core end processing 	1x (0,5 4 mm²), 2x (0,5 1,5 mm²)
connectable conductor cross-section for main contacts	
solid or stranded	0.5 4 mm²

finely stranded with core end processing	0.5 4 mm²	
connectable conductor cross-section for auxiliary contacts		
 solid or stranded 	0.5 2.5 mm²	
 finely stranded with core end processing 	0.5 2.5 mm²	
type of connectable conductor cross-sections		
 for auxiliary contacts 		
— solid	1x (0,5 2,5 mm²), 2x (1,0 1,5 mm²)	
 finely stranded with core end processing 	1x (0.5 2.5 mm²), 2x (0.5 1 mm²)	
 for AWG cables for auxiliary contacts 	1x (20 14), 2x (18 16)	
AWG number as coded connectable conductor cross section		
• for main contacts	20 12	
 for auxiliary contacts 	20 14	
UL/CSA ratings		
operating voltage at AC rated value	480 V	
operational current at AC at 480 V according to UL 508	0.5 A	
Certificates/ approvals		
General Product Approval		EMC



Confirmation







For use in hazardous locations

Functional Safety/Safety of Machinery

Declaration of Conformity

Test Certificates

other

Type Examination Cer**tificate**





Type Test Certificates/Test Report

Confirmation

Railway

Special Test Certific-<u>ate</u>

Further information

Siemens has decided to exit the Russian market (see here).

https://press.siemens.com/global/en/pressrelease/siemens-wind-down-russian-business

Siemens is working on the renewal of the current EAC certificates.

Please contact your local Siemens office on the status of validity of the EAC certification if you intend to import or offer to supply these products to an EAC relevant market (other than the sanctioned EAEU member states Russia or Belarus).

Information on the packaging

https://support.industry.siemens.com/cs/ww/en/view/109813875

Information- and Downloadcenter (Catalogs, Brochures,...)

https://www.siemens.com/ic10

Industry Mall (Online ordering system)

https://mall.industry.siemens.com/mall/en/en/Catalog/product?mlfb=3RM1101-1AA14

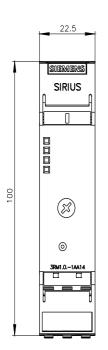
Cax online generator

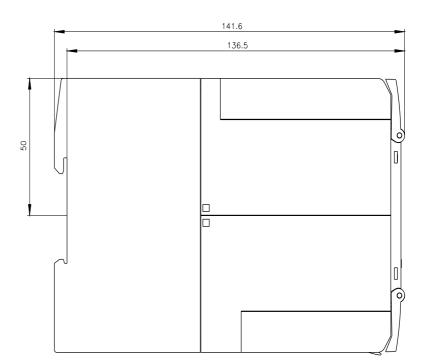
http://support.automation.siemens.com/WW/CAXorder/default.aspx?lang=en&mlfb=3RM1101-1AA14

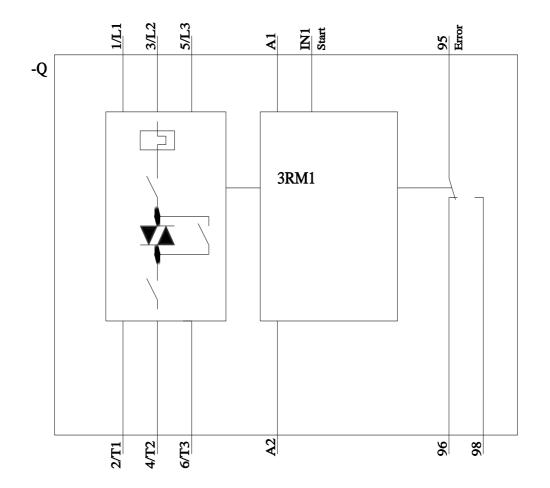
Service&Support (Manuals, Certificates, Characteristics, FAQs,...)

https://support.industry.siemens.com/cs/ww/en/ps/3RM1101-1AA14

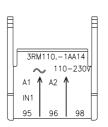
Image database (product images, 2D dimension drawings, 3D models, device circuit diagrams, EPLAN macros, ...) http://www.automation.siemens.com/bilddb/cax_de.aspx?mlfb=3RM1101-1AA14&lang=en

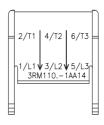












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